

KATHMANDU UNIVERSITY  
End Semester Examination  
June/July, 2023

Marks Scored:

Level : B.E.

Year : II

Exam Roll No. :

Time: 30 mins.

Course : MEEG 206

Semester : II

F. M. : 20

Date :

02 JUL 2023

Registration No.:

SECTION "A"  
[20 Q. × 1 = 20 marks]

Mark [X] in the most appropriate option.

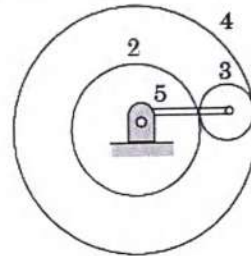
- In a slider crank mechanism, the velocity of piston becomes maximum when  
 the crank is at an angle of  $120^\circ$  with the line of stroke  
 the crank is perpendicular to the line of stroke of the piston  
 the crank and the connecting rod are mutually perpendicular  
 the crank and the connecting rod are in line with each other
- If the rotational speed of a crank of radius 50 cm is 100 rpm and the angular acceleration is  $50 \text{ rad/s}^2$ , then the tangential acceleration of the crank will be  
  $2.5 \text{ m/s}^2$         $25 \text{ m/s}^2$         $0.25 \text{ m/s}^2$         $50 \text{ m/s}^2$
- The mechanism has 7 links with all binary pairs except one which is ternary pair. The number of instantaneous centres of rotation will be  
 14       42       21       13
- A mechanism has 11 links with 1 binary joint, 4 ternary joints and 2 quaternary joints, the degree of freedom of the mechanism will be  
 1       2       -1       0
- For the same lift of the follower and for same angle of action for ascent of the follower in the cams, smaller base circle diameter will give  
 same pressure angle       smaller pressure angle  
 larger pressure angle       depends upon other data
- The centrifugal tension in the belts  
 increases power transmission  
 decreases power transmission  
 increases the wrap angle  
 increases the belt tension without increasing power transmission
- For same pulley diameters, centre distance, belt speed and, belt and pulley materials,  
 open belt drive transmits more power than crossed belt drive  
 crossed belt drive transmits more power than open belt drive  
 open and crossed belt drives transmit same power  
 power transmission does not depend upon open and crossed types of constructions

8. Which of the following is **TRUE** for centrifugal force causing unbalance?  
 direction changes with rotation  
 magnitude changes with rotation  
 direction and magnitude both change with rotation  
 direction and magnitude both remain unchanged with rotation
9. An imaginary circle which by pure rolling action, gives the same motion as the actual gear, is called  
 addendum circle  dedendum circle  clearance circle  pitch circle
10. An unbalanced couple of magnitude 300 N-m is noticed on a shaft of length 200 cm. The dynamic reactions at the bearings are  
 300 N and 300 N  300 N and - 300 N  
 150 N and 150 N  150 N and - 150 N
11. A mass of 9 kg is attached to a shaft at radius of 50 cm, the balance masses  $B_1$  and  $B_2$  are attached on the either side at 50 cm and 100 cm respectively at a radius 50 cm. the plane of rotation of three masses are parallel. If the shaft is rotating at 100 rpm, the balance mass  $B_1$  is  
 3 kg  6 kg  9 kg  12 kg
12. The velocity of sliding \_\_\_\_\_ the distance of the point of contact from the pitch point  
 is directly proportional to  is inversely proportional to  
 is equal to  $\cos\phi$  multiplied by  does not depend upon
13. Cylindrical Cams are also known as  
 Spiral Cam  Conjugate Cam  Drum Cam  Special Cam
14. A cosine curve depicts simple harmonic motion of a cam follower  
 normal stress diagram  acceleration diagram  
 displacement diagram  velocity diagram
15. The pressure angle of cam is the angle between the direction of the follower motion and a normal to the  
 pitch circle  base circle  pitch curve  prime circle
16. In a circular cam with roller follower, the acceleration in any position of the lift will depend only upon  
 total lift, total angle of lift, minimum radius of cam and cam speed  
 cam speed, radius of circular arc, diameter of roller and total lift  
 total lift, cam speed, radius of cam and radius of roller  
 total lift, cam speed and total angle of lift
17. Which one of the following is used to convert a rotational motion into a translational motion?  
 bevel gears  double helical gears  
 worm gears  rack and pinion gears

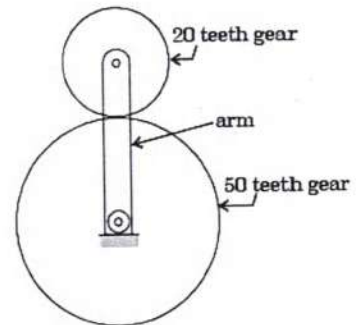
18. Planar closed kinematic chain is formed with rigid links  $PQ = 2$  m,  $QR = 3$  m,  $RS = 2.5$  m and  $SP = 2.7$  m with all revolute joints. The link to be fixed to obtain a double crank mechanism is  
 PQ                       QR                       RS                       SP

19. In the gear train shown gear 3 is carried on arm 5, gear 3 meshes with gear 2 and gear 4. The number of teeth in gear 2, 3 and 4 are 60, 20 and 100 respectively. If gear 2 is fixed and gear 4 rotates with an angular velocity of 100 rpm in the counterclockwise direction, the angular speed of arm 5 in rpm is

- 166.7 counterclockwise  
 166.7 clockwise  
 62.5 counterclockwise  
 62.5 clockwise



20. The number of degree of freedom of the planetary gear train as shown in the figure is  
 0                       1                       2                       3

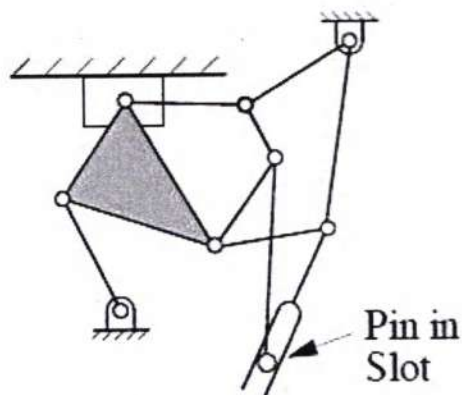


SECTION "B"

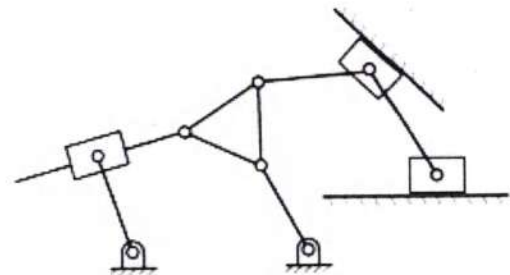
Attempt ALL questions. Assume suitable data if necessary.

1.

- a. Determine the degrees of freedom of the linkages shown in the figure below. [4]



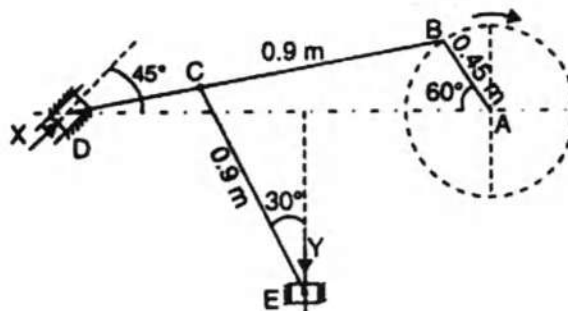
(i)



(ii)

- b. A mechanism in which the crank AB is rotating uniformly at 180 rpm in the clockwise direction is shown in the figure below. The blocks at D and E are working in frictionless guides. The dimensions of the mechanism are: AB = 450 mm; BD = 1500 mm; BC = 900 mm and CE = 900 mm. [8]

- Draw the velocity diagram
- Determine the velocities of blocks D and E in their guides.
- Determine the angular velocity of point C
- Find the turning moment at A if a force of 1000 N acts on D in the direction of arrow X and a force of 1500 N acts on E in the direction of arrow Y.



- c. Explain four bar chain mechanism with all of its inversion [3]

2. Construct a follower performance diagram and draw the cam profile for the cam rotating in anticlockwise direction for the following conditions.

Type of follower used is knife edge follower with in line cam, Follower rises by 24 mm with simple harmonic motion in  $1/4$  rotation of the cam, dwells for  $1/8$  rotation of the cam and then raises again by 24 mm with uniform velocity in  $1/4$  rotation of the cam, dwells for  $1/16$  rotation of the cam and finally return to the initial position for the remaining period of the cam rotation with simple harmonic motion. Take base circle radius of 30 mm. Also calculate the maximum velocity and acceleration of the follower during the return stroke. [11]

3.

- a. State law of gearing. A spur gear has a module of 2 mm and its pitch line velocity is 0.6283 m/sec. If the number of teeth of this spur gear is 30, find the speed of the gear. Also determine its circular pitch and diametral pitch. The gear is in mesh with other spur gear of same number of teeth having 20 degree involute profile, determine the height of addendum if the length of path of contact is 1.8 times the circular pitch. [6]
- b. What is the interference in gears? Explain the method to avoid or reduce the interference in an external involute spur gear pair. [3]

4. A motor shaft connected to a pulley 120 cm diameter running at 200 rpm is required to drive a machine shaft at 800 rpm in the opposite direction. The belt drive is required to transmit 9 kW from motor shaft to machine shaft with a leather belt of length 3 m and thickness 10 mm. If the safe working stress for the leather belt is  $140 \text{ N/cm}^2$ , the mass density of leather is  $1 \text{ gm/cm}^3$  and the coefficient of friction between leather belt and pulley is 0.3, determine the width of the belt. [6]

5. A rotating shaft carries four rotating masses A, B, C and D in the order D C B and A from the left end along its axis. The mass A may be assumed concentrated at a radius of 12 cm, B at 15 cm, C at 14 cm and D at 18 cm. The masses A, C and D are 15 kg, 10 kg and 8 kg respectively. The planes of rotation of A and B are 15 cm apart and of B and C are 18 cm apart. The angle between the radii of A and C is 90 degree. If the shaft is in complete dynamic balance, determine [7]
- the angular position of B and D with respect to A
  - the distance between the planes of revolution of C and D, and
  - the mass B.

6. The gears A, D and E in a compound epicyclic gear train as shown in the figure, are free to rotate on the axis P. The compound gear B and C rotate together on the axis Q at the end of arm F. All the gears have equal module. The number of external teeth on the gears A, B and C are 18, 45 and 21 respectively. The gears D and E are annular gears. The gear A rotates at 90 rpm in the anti-clockwise direction and the gear D rotates at 450 rpm clockwise. Find the speed and direction of the arm F and gear E. [7]

