

KATHMANDU UNIVERSITY  
End Semester Examination  
June/July, 2023

Marks Scored:

Level : B.Sc.  
Year : III

Course : MATH 327  
Semester : II

Exam Roll No. :

Time: 30 mins.

F. M. : 10

Registration No.:

Date :

SECTION "A"

[10Q.  $\times$  0.5 = 5 marks]

Fill in the blank space(s) by writing the most appropriate word(s) or symbol(s).

1. If  $\gcd(a, b) = d$ , then  $\gcd(a/d, b/d) =$  \_\_\_\_\_.
2. Let  $d = \gcd(a, b)$  and  $n \in \mathbb{N}$ . If  $d|c$  and  $(x_0, y_0)$  is a solution of Diophantine equation  $ax + by = c$ , then all the integers solution is given by \_\_\_\_\_.
3. If  $a$  and  $b$  are relatively prime positive integers, then the arithmetic progression  $a, a + b, a + 2b, a + 3b \dots$  contains \_\_\_\_\_ primes.
4. A number-theoretic function  $f$  is said to be multiplicative if \_\_\_\_\_, whenever  $\gcd(m, n) = 1$ .
5. Let  $p$  be a prime and  $m$  a positive integer, then  $\varphi(p^m) =$  \_\_\_\_\_.
6. If  $f(n)$  is an arithmetic function, then  $F(18) \sum_{d|18} f(d) =$  \_\_\_\_\_.
7. 561 is a base \_\_\_\_\_ pseudo-prime.
8.  $\left[ \frac{53}{59} \right] =$  \_\_\_\_\_, the sign  $[ ]$  has usual meaning.
9. The set of reduced residue system modulo 8 is \_\_\_\_\_.
10. Let  $p$  be a prime and suppose that  $p$  does not divide  $a$ . Then \_\_\_\_\_.

SECTION "B"

[10Q.  $\times$  0.5 = 5 marks]

Fill in the blank space(s) by selecting the most appropriate answer from among the given ones. (DO NOT TICK THE ANSWER).

11. If  $a, b \in \mathbb{Z}$  and  $b \neq 0$ , then  $\exists$  a unique pair of integer  $q$  and  $r$ , such that  $a = bq + r$  where \_\_\_\_\_.  
a.  $0 \leq r \leq |b|$       b.  $0 \leq r < |b|$       c.  $0 > r > |b|$       d.  $0 \leq r \leq b$
12. Let  $d = (a, m)$  then the congruence  $ax \equiv b \pmod{m}$  has a solution iff \_\_\_\_\_.  
a.  $b|d$       b.  $m|d$       c.  $d|b$       d.  $a|d$



KATHMANDU UNIVERSITY  
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Time : 2 hrs. 30 mins.

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Semester : II  
F. M. : 50

SECTION "C"

[6Q. × 7 = 42 marks]

1. Prove that if  $d$  is a common divisor of  $a$  and  $b$  then  $d = \gcd(a, b)$  if and only if  $\gcd\left(\frac{a}{d}, \frac{b}{d}\right) = 1$ . We have an unknown number of coins. If you make 77 strings of them, you are 50 coins short; but if you make 78 strings, it is exact. How many coins are there? [3+4]
2. Define a linear congruence *modulo*  $n$ . Prove that if  $ca \equiv cb \pmod{n}$ , then  $a \equiv b \pmod{\frac{n}{d}}$ , where  $d = \gcd(c, n)$ . Find the solution of the given system of congruence. [1+2+4]

$$\begin{aligned}6x + 8y &\equiv 10 \pmod{13} \\6x + 15y &\equiv 21 \pmod{13}\end{aligned}$$

**OR**

Define congruence modulo. State Chinese Remainder theorem. A certain integer between 1 and 1200 leaves the remainders 1, 2, 6 when divided by 9, 11, 13 respectively. What is the integer?

3. State and prove Wilson's Theorem. Make a concrete example that should help to clarify the proof of Wilson's theorem. [1+3+3]
4. Define the order of integer modulo  $n$ . Find the order of integers 2 Modulo 17. Make the table of the indices for a primitive root of 11 and then solve the given congruence  $7x^3 \equiv 3 \pmod{11}$ . [1+2+4]
5. Define Number-theoretic function. Prove that  $\sigma, \tau, \mu$  are Number-theoretic functions, these symbols having their usual meaning. [1+6]
6. Define RSA Cryptosystem. Write RSA Algorithm. Write an example performing encryption and decryption a message using RSA algorithm. [1+3+3]

SECTION "D"

[4Q. × 2 = 8 marks]

7. Verify that the integers 1949 and 1951 are twin prime.
8. Use Fermat's theorem to verify that 17 divides  $11^{104} + 1$ .
9. Verify that the equality  $\phi(n) = \phi(n + 1) = \phi(n + 2)$  holds when  $n = 5186$ .
10. Show that  $85 = 5 \cdot 17$  is a base 4 pseudo-prime but not a base 2 pseudo-prime.

25 JUN 2023

**Single Phase Half Wave Diode Rectifier:****With R Load:**

- **RMS value of output voltage**

$$V_{o(rms)} = \frac{V_m}{2}$$

$V_m$  = Maximum value of source voltage ( $V_s$ )

- **Average value of output voltage,**

$$V_{o(OC)} = \frac{V_m}{\pi}$$

- Average value of output voltage,
- Power delivered  $P = I_{o(rms)}^2 \cdot R$

$$I_{o(rms)} = \text{rms value of load current} = \frac{\text{Power delivered to load}}{\text{Input } V_s}$$

- Input power Factor =  $\frac{V_{o(rms)} \cdot I_{o(rms)}}{V_s \cdot I_{o(rms)}} = 0.707$

**With L load:**

- Output current  $I_o = \frac{V_m}{\omega L} (1 - \cos \omega t)$

- Maximum value of current  $I_o = \frac{2X_m}{\omega L}$

- Average value of current  $I_o = \frac{I_{max}}{2}$

- RMS value of fundamental current

$$I_{1(rms)} = \frac{I_o}{\sqrt{2}}$$

- Output voltage  $V_o = V_m \sin \omega t = V_s$
- Average value of current voltage  $V_o = 0$

**With C Load:**

- Output voltage  $V_o = V_m \sin \omega t = V_s = V_c$
- Diode voltage  $V_D = V_m (\sin \omega t - 1)$
- Output current  $I_o = \omega C V_m \cos \omega t$
- Average value of diode voltage  $V_D = V_m$
- RMS value of diode voltage

$$V_{rmsD} = 1.225 V_m$$

**Single-Phase Full wave Mid-point Diode Rectifier:**

Average output voltage,

$$V_o = \frac{1}{\pi} \int_0^\pi V_m \sin \omega t d(\omega t)$$

$$V_o = \frac{2V_m}{\pi}$$

Average output current,

$$I_o = \frac{V_o}{n}$$

Rms value of load voltage,

$$V_{o(rms)} = \sqrt{\frac{1}{2\pi} \int_0^\pi V_m^2 \sin^2 \omega t d(\omega t)}$$

$$V_{o(rms)} = \frac{V_m}{\sqrt{2}} = V_s$$

Rms value of load current,

$$I_{o(rms)} = \frac{V_s}{R}$$

Power delivered to load =  $V_{o(rms)} I_{o(rms)}$

$$\therefore \text{Input power factor} = \frac{V_{o(rms)} I_{o(rms)}}{V_s I_{o(rms)}}$$

**Single-Phase Full wave Diode Bridge Rectifier:**

Average value of diode current,

$$I_o = \frac{1}{2\pi} \int_0^\pi I_m \sin \omega t d(\omega t) = \frac{I_m}{\pi}$$

Rms value of diode current,

$$I_{o(rms)} = \sqrt{\frac{1}{2\pi} \int_0^\pi I_m^2 \sin^2 \omega t d(\omega t)}$$

$$I_{o(rms)} = \frac{I_m}{2}$$

**Single phase half wave-controlled rectifier with R Load**

Average output voltage,

$$V_o = \frac{V_m}{2\pi} (1 + \cos \alpha)$$

Average output current,

$$I_o = \frac{V_m}{2\pi R} (1 + \cos \alpha)$$

Rms value of output voltage,

$$V_{or} = \frac{V_m}{2\sqrt{\pi}} \left[ (n - \alpha) + \frac{1}{2} \sin 2\alpha \right]^{1/2}$$

Commutation time or turn off time of the thyristor,

$$t_c = \frac{\pi}{\omega} \text{ sec}$$

Input power factor of the converter,

$$\text{p.f.} = \frac{V_{or} I_{or}}{V_s I_{or}} = \frac{1}{\sqrt{2\pi}} \left[ n - \alpha + \frac{1}{2} \sin 2\alpha \right]^{1/2}$$

**Single phase half wave-controlled rectifier with RL load:**

Average output voltage,

$$V_o = \frac{V_m}{2n} (\cos \alpha - \cos \beta)$$

Average output current,

$$I_o = \frac{V_m}{2nR} (\cos \alpha - \cos \beta)$$

Rms value of output voltage.

$$V_{or} = \frac{V_m}{2\sqrt{n}} \left[ (\beta - \alpha) - \frac{1}{2} (\sin 2\beta - \sin 2\alpha) \right]^{\frac{1}{2}}$$

Commutation time or turn off time for the thyristor,

$$t_c = \frac{2n - \beta}{\omega} \text{ sec}$$

**Single phase half wave-controlled rectifier with RLE load:**

The minimum value of firing angle at which thyristor can be triggered is

$$\theta_1 = \sin^{-1} \left( \frac{E}{V_m} \right)$$

Average output current,

$$I_o = \frac{1}{2nR} [V_m (\cos \alpha - \cos(\gamma + \alpha)) - E\gamma]$$

Average output voltage,

$$V_o = \frac{1}{2n} [V_m (\cos \alpha - \cos \beta) + E(2\pi + \alpha - \beta)]$$

Input power factor,

$$p.f. = \frac{(I_o^2 R + E I_o)}{V_o I_o}$$

Commutation time or turn off time of thyristor,

$$t_c = \frac{2n - \beta}{\omega} \text{ sec}$$

**Bridge Inverter:** Bridge circuits are commonly used in DC-AC conversion. Moreover, an output transformer is not essential in a bridge circuit.

**1 $\phi$  Half Bridge Inverter** - The output voltage  $V_o = \sum_{n=1,3,5}^{\infty} \frac{2V}{n\pi} \sin n\omega t$

**1 $\phi$  Full Bridge Inverter** - The output voltage

$$V_o = \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \sin n\omega t$$

Where, n = order of harmonic

$\omega = 2\pi f$ , is frequency of the output voltage in rad/sec

**Key points:**

- The load impedance ( $Z_n$ ) at frequency

$$|Z_n| = \left[ R^2 + \left( n\omega L - \frac{1}{n\omega C} \right)^2 \right]^{\frac{1}{2}}$$

- Phase angle, ( $\theta_n$ ),  $\theta_n = \tan^{-1} \frac{\left[ n\omega L - \frac{1}{n\omega C} \right]}{R}$  rad

- Output current or load current at the instant of commutation  $I_o = I_n = \frac{V_o}{Z_n}$  or  $\omega t = \pi$  rad

- Fundamental load power

$$(P_o)_1 = I_1^2 R = V_{o1} I_{o1} \cos \phi_1$$

**Three Phase Half Wave Diode Rectifier:**

The peak inverse voltage (PIV) =  $\sqrt{3} V_{mp}$  for each of the three diode  $D_1$ ,  $D_2$  and  $D_3$ . The average output voltage.

$$\begin{aligned} V_o &= \frac{1}{2n/3} \int_{\pi/6}^{5\pi/6} V_{mp} \sin \omega t \, d(\omega t) \\ &= \frac{3\sqrt{3}}{2n} V_{mp} \\ &= \frac{3\sqrt{6}}{2n} V_{pn} \quad (\because V_{mp} = \sqrt{2} V_{pn}) \\ &= \frac{3}{2n} V_{ms} \quad (\because V_{ms} = \sqrt{3} V_{mp} = \sqrt{6} V_{pn}) \end{aligned}$$

Rms value of output voltage,

$$V_{o(rms)} = \sqrt{\frac{3}{2n} \int_{\pi/6}^{5\pi/6} V_{mp}^2 \sin^2 \omega t \, d(\omega t)}$$

$$V_{o(rms)} = 0.84068 V_{mp}$$

**Three-Phase Mid-point 6-Pulse Diode Rectifier:**

Average output voltage,

$$V_o = \frac{1}{n/3} \int_{\pi/3}^{2\pi/3} V_{mp} \sin \omega t \, d(\omega t)$$

$$V_o = \frac{3V_{mp}}{n}$$

Rms value of output voltage,

$$V_{o(rms)} = \sqrt{\frac{1}{n/3} \int_{\pi/3}^{2\pi/3} (V_{mp} \sin \omega t)^2 \, d(\omega t)}$$

$$V_{o(rms)} = 0.9558 V_{mp}$$

**THREE PHASE DIODE BRIDGE RECTIFIER**

Average Value of load voltage,

$$V_o = \frac{1}{n/3} \int_{\pi/3}^{2\pi/3} V_{ms} \sin \omega t \, d(\omega t)$$

$$V_o = \frac{3V_{ms}}{n}$$

Rms value of output voltage,

$$V_{o(rms)} = \sqrt{\frac{1}{n/3} \int_{\pi/3}^{2\pi/3} V_{ms}^2 \sin^2 \omega t \, d(\omega t)}$$

$$V_{o(rms)} = 0.9558 V_{ms}$$

### THREE PHASE HALF-WAVE-CONTROLLED RECTIFIER:

If  $V_{mp}$  is the peak value of phase voltage, the average value of the output voltage,

$$V_o = \begin{cases} \frac{3\sqrt{3}}{2\pi} V_{mp} \cos \alpha & ; \text{for } 0 < \alpha < 30^\circ \\ \frac{3}{2\pi} V_{mp} (1 + \cos(\alpha + 30^\circ)) & ; \text{for } 30^\circ < \alpha < 150^\circ \end{cases}$$

If  $V_{ml}$  is the peak value of line voltage, average output voltage,

$$V_o = \frac{3V_{ml}}{\pi} \cos \alpha$$

If  $I_0$  is the load current, average value of source current,

$$I_s = I_0 \sqrt{\frac{2}{3}}$$

Average value of thyristor current,

$$I_t = I_0 \sqrt{\frac{1}{3}}$$

### Three phase half-wave converter drive

1.  $V_m = \sqrt{2}V_s$
2. Average value of output voltage  $V_o = \frac{3V_m}{2\pi} \cos \alpha$  [For  $0 \leq \alpha \leq \pi$ ]
3. RMS value of phase or line current  $I_s = I_a \sqrt{\frac{1}{3}}$
4. Average thyristor current  $I_{TA} = I_a \frac{1}{3}$
5. RMS thyristor current  $I_{TR} = I_a \sqrt{\frac{1}{3}}$
6. Input PF =  $\frac{V_o * I_a}{\sqrt{3} * V_s * I_s} = \frac{3}{\pi\sqrt{2}} \cos \alpha$

### Three phase Full-wave converter drive

1. Average value of armature voltage  $V_o = \frac{3V_m}{\pi} \cos \alpha$  [For  $0 \leq \alpha \leq \pi$ ]
2. Average value of field voltage  $V_f = \frac{3V_m}{\pi} \cos \alpha_f$  [For  $0 \leq \alpha_f \leq \pi$ ]
3. RMS value of line current  $I_s = I_a \sqrt{\frac{2}{3}}$
4. Average thyristor current  $I_{TA} = I_a \frac{1}{3}$
5. RMS thyristor current  $I_{TR} = I_a \sqrt{\frac{1}{3}}$
6. Input PF =  $\frac{V_o * I_a}{\sqrt{3} * V_s * I_s} = \frac{3}{\pi} \cos \alpha$

### Three phase Dual converter drive

1. Average value of output and field circuit voltage  $V_f = \frac{3V_m}{\pi} \cos \alpha_f$  for  $0 \leq \alpha_f \leq \pi$

### Three phase semi converter drive

1. Average value of armature voltage  $V_o = \frac{3V_m}{2\pi} (1 + \cos \alpha_s)$  [For  $0 \leq \alpha_s \leq \pi$ ]
2. Average value of field voltage  $V_f = \frac{3V_m}{2\pi} (1 + \cos \alpha_f)$  [For  $0 \leq \alpha_f \leq \pi$ ]
3. RMS value of line current  $I_s = I_a \sqrt{\frac{2}{3}}$  [For  $\alpha < 60^\circ$ ]
4. RMS thyristor current  $I_{TR} = I_a \sqrt{\frac{1}{3}}$  [For  $\alpha < 60^\circ$ ]
5. Average thyristor current  $I_{TA} = I_a \frac{1}{3}$  [For  $\alpha < 60^\circ$ ]
6. RMS value of line current  $I_s = I_a \sqrt{\frac{180 - \alpha}{180}}$  [For  $60^\circ < \alpha < 180^\circ$ ]
7. RMS thyristor current  $I_{TR} = I_a \sqrt{\frac{180 - \alpha}{360}}$  [For  $60^\circ < \alpha < 180^\circ$ ]
8. Average thyristor current  $I_{TA} = I_a * (\frac{180 - \alpha}{360})$  [For  $60^\circ < \alpha < 180^\circ$ ]
9. Freewheeling diode RMS current  $I_{FR} = I_a * \sqrt{\frac{\alpha - 60}{120}}$  [For  $60^\circ < \alpha < 180^\circ$ ]
10. Freewheeling diode average current  $I_{FA} = I_a * \frac{\alpha - 60}{120}$  [For  $60^\circ < \alpha < 180^\circ$ ]
11. Input PF =  $\frac{V_o * I_a}{\sqrt{3} * V_s * I_s} = \frac{3}{2\pi} (1 + \cos \alpha)$  [For  $\alpha < 60^\circ$ ]
12. Input PF =  $\frac{V_o * I_a}{\sqrt{3} * V_s * I_s} = \frac{\sqrt{6}(1 + \cos \alpha)}{2\pi} \sqrt{\frac{\pi - \alpha}{\pi}}$  [For  $60^\circ < \alpha < 180^\circ$ ]