

Level : B. E.

Course : ETEG 305

Year : III

Semester : II

Exam Roll No. :

Time: 30 min

F. M. : 10

Registration No.:

Date: SEP 10 2017

SECTION "A"  
[20 Q × 0.5 = 10 marks]

Choose the most appropriate option. Symbols have their usual meaning.

- Which of the following discrete time signal represents the energy signal?  
a.  $(1/2)^n u(n)$       b.  $\sin(\frac{\pi}{3})n$       c.  $nu(n)$       d.  $e^{[(\pi/3)n + (\pi/2)]}$
- If  $Z[x(n)]$  is  $X(z)$  then  $Z[nx(n)]$  is given by  
a.  $Z \frac{dX(z)}{dz}$       b.  $(1/z) \frac{dX(z)}{dz}$       c.  $(-1/z) \frac{dX(z)}{dz}$       d.  $-Z \frac{dX(z)}{dz}$
- The number of complex multiplications in computation of N-point DFT by radix -2 DIT-FFT is \_\_\_\_\_.  
a.  $N \log_2 N$       b.  $(1/N) \log_2 N$       c.  $\frac{N}{2} \log_2 N$       d.  $\frac{N}{2} \log_{10} N$
- For the analog signal  $x(t) = 3\cos 100\pi t$ , what is the corresponding discrete-time signal if the signal is sampled at 75Hz?  
a.  $3\cos \pi n$       b.  $3\cos(\pi/3)n$       c.  $3\cos(3\pi/2)n$       d.  $3\cos(2\pi/3)n$
- The DFT of  $x(n)$  is defined as  
a.  $X(k) = X(\omega)|_{\omega=2\pi k}$       b.  $X(k) = X(\omega)|_{\omega=2\pi n/N}$   
c.  $X(k) = X(\omega)|_{\omega=2\pi n}$       d.  $X(k) = X(\omega)|_{\omega=2\pi k/N}$
- If reverse polynomial of  $A_m(z)$  is  $B_m(z)$ , which of the following expression is correct?  
a.  $B_m(z) = z^{-m} A_m(z^{-1})$       b.  $B_m(z) = z^m A_m(z^{-1})$   
c.  $B_m(z) = z^{-m} A_m(z)$       d.  $B_m(z) = z^{-1} A_m(z^{-1})$
- The filter structure which uses less number of delay element is \_\_\_\_\_  
a. Direct form-I      b. Direct form-II      c. Cascade form      d. Parallel form
- If  $Z[x(n)]$  is  $X(z)$  then initial value theorem states that  
a.  $x(0) = \lim_{z \rightarrow \infty} zX(z)$       b.  $x(0) = \lim_{z \rightarrow \infty} (z-1)X(z)$   
c.  $x(0) = \lim_{z \rightarrow 0} zX(z)$       d.  $x(0) = \lim_{z \rightarrow \infty} X(z)$
- A system whose output  $y(n)$  at time  $n$  depends on any number of past output values is called a \_\_\_\_\_  
a. Recursive system      b. Non-recursive system  
c. Causal system      d. Non-causal system
- Inverse Fourier transform of  $X(\omega) = e^{-j\omega} (1 + \cos \omega)$  is equal to \_\_\_\_\_  
a.  $\sin \frac{\pi n}{\pi n}$       b.  $\cos \frac{\pi n}{\pi n}$       c.  $\sin \frac{\pi(n-1)}{\pi(n-1)}$       d.  $\cos \frac{\pi(n-1)}{\pi(n-1)}$



Level : B. E.

Year : III

Time : 2 hrs. 30 mins.

Course : ETEG 305

Semester : II

F. M. : 40

SECTION "B"

[4Q. × 10 = 40 marks]

Attempt *ANY FOUR* questions. Figure in the margin indicates the full mark. Students are required to answer in their own words as far as practicable.

1. a. Determine the unit sample response,  $h(n)$  of the system characterized by the difference equation:
 
$$y(n) = 2.5 y(n-1) - y(n-2) + x(n) - 5x(n-1) + 6x(n-2) \quad [3]$$
- b. Check mathematically whether the discrete time ramp signal is energy signal, power signal or neither power nor energy signal. [2]
- c. Perform the circular convolution of the following two sequences. Also write the circular convolution property of DFT.
 
$$x(n) = \{2, 1, 2, 1\} \text{ and } x(n) = \{1, 2, 3, 4\} . \quad [5]$$
2. a. Find the Z-transform of signal  $x(n) = a^n (\cos \omega_0 n) u(n)$ . Also, explain that the Z-transform cannot uniquely specify the signal in time domain. [2+1]
- b. Given a three stage lattice filter with coefficients  $K_1 = 1/4$ ,  $K_2 = 1/2$ ,  $K_3 = 1/3$ , determine the FIR filter coefficients for the direct form structure. Also draw the direct form-II structure. [5]
- c. Differentiate between FIR filters and IIR filters. [2]
3. a. Convert the Analog filter with the following system function:
 
$$H_a(s) = (s+0.1)/((s+0.1)^2 + 16)$$
 into a digital filter by means of bilinear transformation. The digital filter is to have a digital resonant frequency of  $\omega = \pi/2$  [3]
- b. Compute the IDFT of the sequence using DIF-FFT algorithm: [5]

$$X(k) = \{7, -0.707 - j0.707, -j, 0.707 - j0.707, 1, 0.707 + j0.707, j, -0.707 + j0.707\}$$
- c. Determine the causal signal  $x(n)$  having the Z-transform
 
$$X(z) = \frac{1}{(1+z^{-1})(1-z^{-1})^2} \quad [2]$$
4. a. A low pass digital filter has the desired frequency response as shown: [6]

$$H_d(e^{j\omega}) = \begin{cases} e^{-j\omega \frac{(M-1)}{2}}, & 0 \leq |\omega| \leq \pi/2 \\ 0, & \pi/2 \leq |\omega| \leq \pi \end{cases}$$
 Design a FIR filter using frequency sampling method for order,  $M = 7$
- b. List some advantages of DSP processors over conventional microprocessors. [2]
- c. How phase distortion and delay distortion are introduced in FIR filters? Write the conditions for linear phase digital filters. [2]
5. a. Check whether the corresponding LTI system with system function
 
$$H(z) = -1 - 0.4z^{-1}/(1 - 2.8z^{-1} + 1.6z^{-2})$$
 is stable and causal if ROC is: [2]
  - i)  $|z| > 2$
  - ii)  $|z| < 0.8$
  - iii)  $0.8 < |z| < 2$
- b. Design a Butterworth digital filter using bilinear transformation method. The specifications of the desired low pass filter are given by [6]

$$0.9 \leq |H(e^{j\omega})| \leq 1 \quad \text{for } 0 \leq |\omega| \leq \pi/2$$

$$|H(e^{j\omega})| \leq 0.2 \quad \text{for } \frac{3\pi}{4} \leq |\omega| \leq \pi \quad (\text{Assume sampling period} = 1 \text{ sec})$$
- c. What are the factors that influence the choice of structure for realization of an LTI system? [2]

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